Second Order Sufficient Conditions Under Weak Assumptions for State Constrained Optimal Control Problems

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Abstract: Second order sufficient optimality conditions (SSC) are derived, for an optimal control problem subject to mixed control-state and pure state constraints of order one. The proof is based on a Hamilton-Jacobi inequality and it exploits regularity of the control function, as well as the associated Lagrange multipliers. The obtained (SSC) involve Legendre-Clebsch conditions and solvability of an auxiliary Riccati equation. They are weakened by taking into account the strongly active constraints.

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